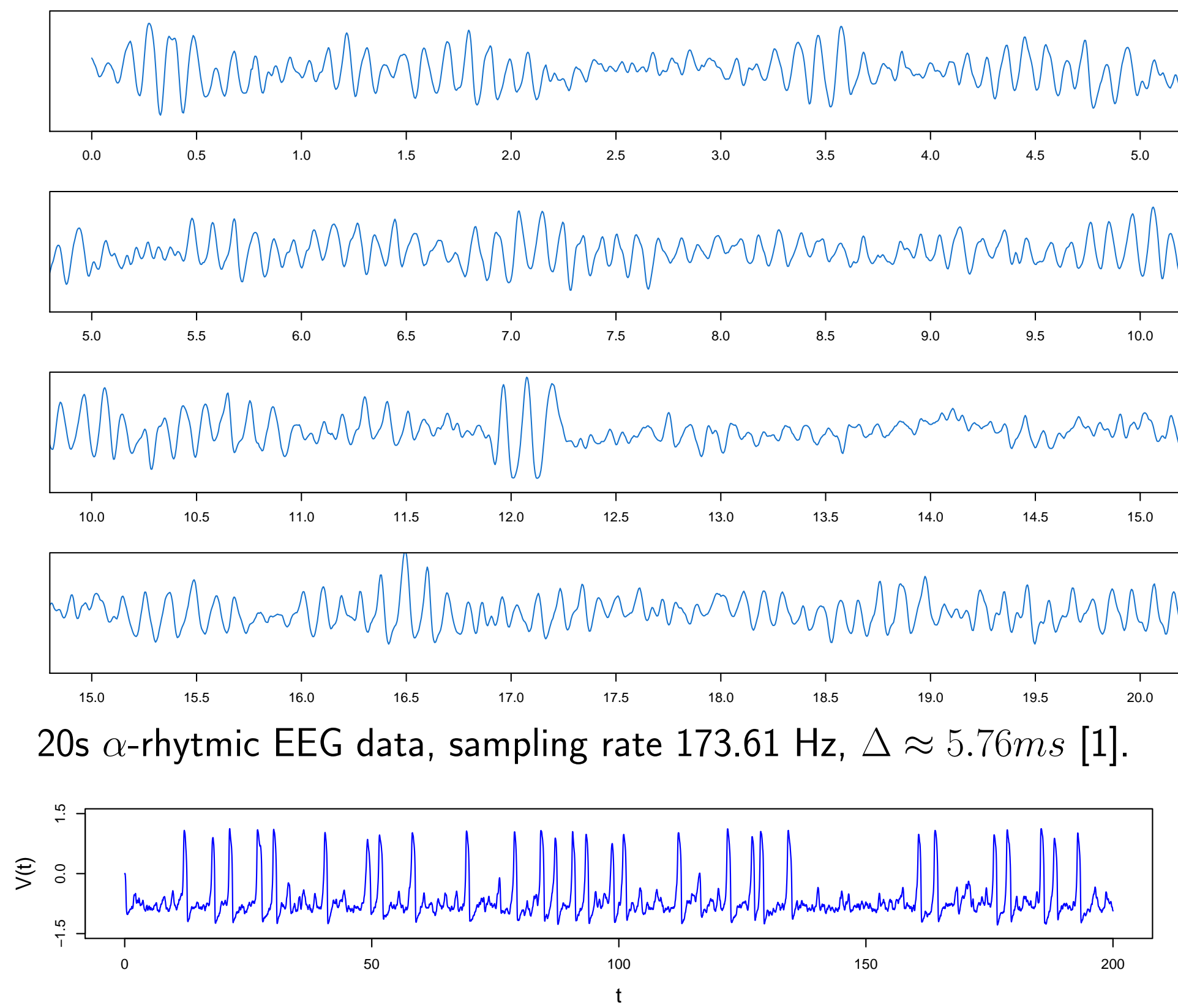


Structure-preserving Approximate Bayesian Computation for complex stochastic models

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Considered neural recordings



20s α -rhythmic EEG data, sampling rate 173.61 Hz, $\Delta \approx 5.76$ ms [1].

Stochastic models and setting of interest

X : d -dimensional stochastic process depending on $\theta \in \Theta \subseteq \mathbb{R}^k$,
 $dX_t = F(X_t; \theta)dt + \Sigma(X_t; \theta)dW_t$, $t \in [0, T]$, $\theta \in \Theta \subseteq \mathbb{R}^m$
 X, F and W d -dimensional, Σ : $d \times d$ matrix. State space: $D \subseteq \mathbb{R}^d$.

Model properties

- It exists an invariant distribution.
- X partially observed via $Y_\theta = g(X)$, $g: \mathbb{R}^d \rightarrow \mathbb{R}^m$.
- The noise may not enter in all components (Σ_{ii} may be 0).

1. Stochastic Harmonic Oscillator

$$d \begin{pmatrix} Q_t \\ P_t \end{pmatrix} = \begin{pmatrix} P_t \\ -\lambda^2 Q_t - 2\gamma P_t \end{pmatrix} dt + \begin{pmatrix} 0 \\ \sigma \end{pmatrix} dW_t, \quad X_0 = x_0.$$

with $\lambda^2 - \gamma^2 > 0$ (weakly damped case), $\theta = (\lambda, \gamma, \sigma)$ and $Y_\theta = Q$.

2. Stochastic Jensen and Rit neural mass model (JRNMM)

$$d \begin{pmatrix} X_{1,t} \\ X_{2,t} \\ X_{3,t} \\ X_{4,t} \\ X_{5,t} \\ X_{6,t} \end{pmatrix} = \begin{pmatrix} X_{4,t} \\ X_{5,t} \\ X_{6,t} \\ Aa s(X_{2,t} - X_{3,t}) - 2aX_{4,t} - a^2X_{1,t} \\ Aa(\mu + C_2 s(C_1 X_{1,t})) - 2aX_{5,t} - a^2X_{2,t} \\ BbC_4 s(C_3 X_{1,t}) - 2bX_{6,t} - b^2X_{3,t} \end{pmatrix} dt + \begin{pmatrix} 0 \\ 0 \\ 0 \\ \tau \\ \sigma \\ \tau \end{pmatrix} dW_t$$

with $X_0 = x_0, C_1 = C, C_2 = 0.8C, C_3 = C_4 = 0.25C$,
 $\theta = (\sigma, \mu, C)$ and $Y_\theta = X_2 - X_3$.

3. Stochastic FitzHugh-Nagumo (FHN)

$$d \begin{pmatrix} V_t \\ U_t \end{pmatrix} = \begin{pmatrix} \frac{1}{\epsilon}(V_t - V_t^3 - U_t) \\ \gamma V_t - U_t + \beta \end{pmatrix} dt + \begin{pmatrix} 0 \\ \sigma \end{pmatrix} dW_t, \quad X_0 = x_0.$$

$\theta = (\epsilon, \gamma, \beta, \sigma)$ and $Y_\theta = V$.

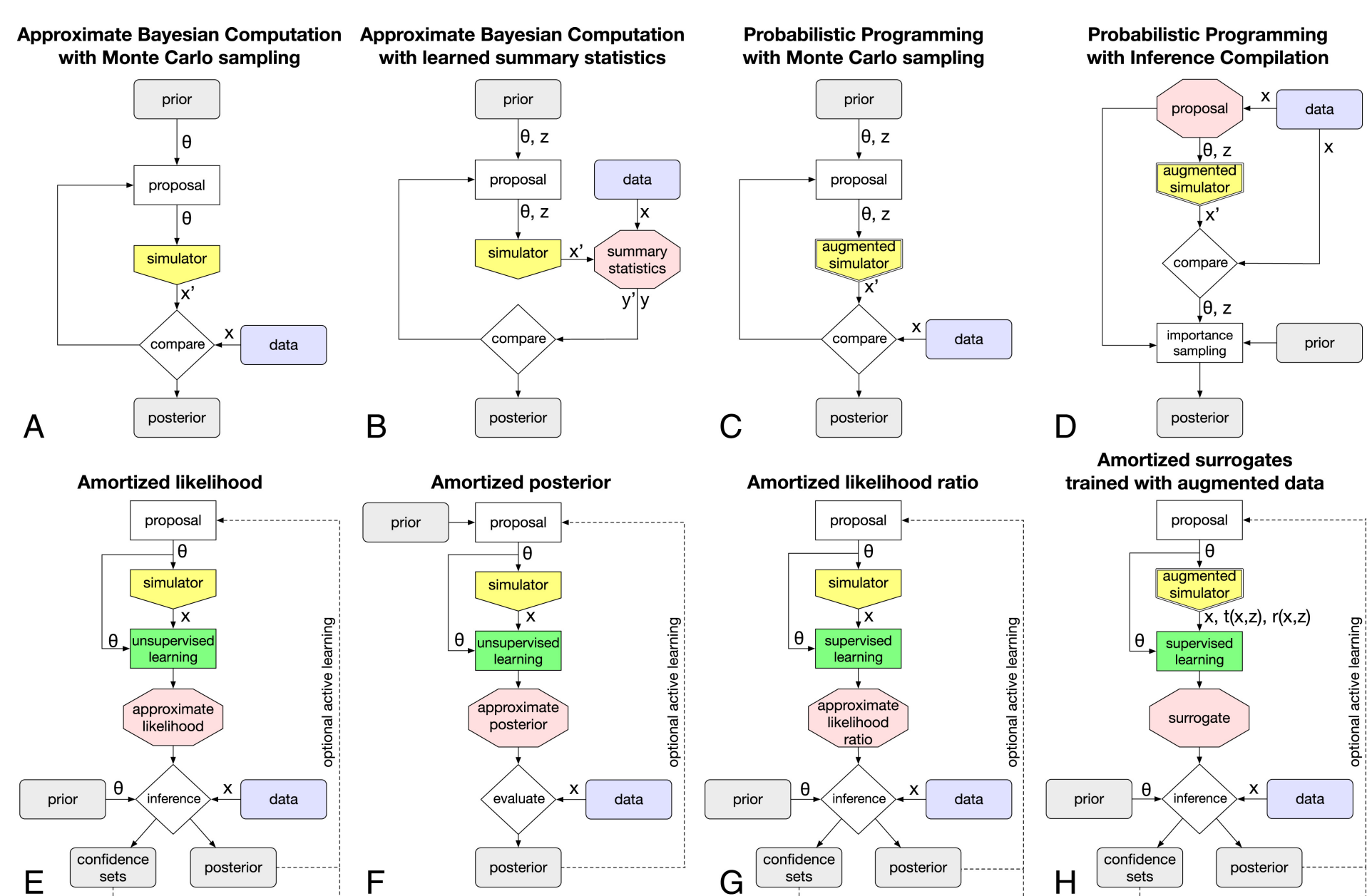
Simulation-based inference

Goal: Estimate θ based on the available partial observations Y_θ .

Challenge: The underlying likelihood is intractable!

$$\underbrace{\pi(\theta|y)}_{\text{posterior}} \propto \underbrace{\pi(y|\theta)}_{\text{likelihood (intractable)}} \underbrace{\pi(\theta)}_{\text{prior}}$$

\Rightarrow Likelihood-free approaches, here simulation-based inference, in particular Approximate Bayesian Computation (ABC) [2].



Overview of different approaches to simulation-based inference from [3].

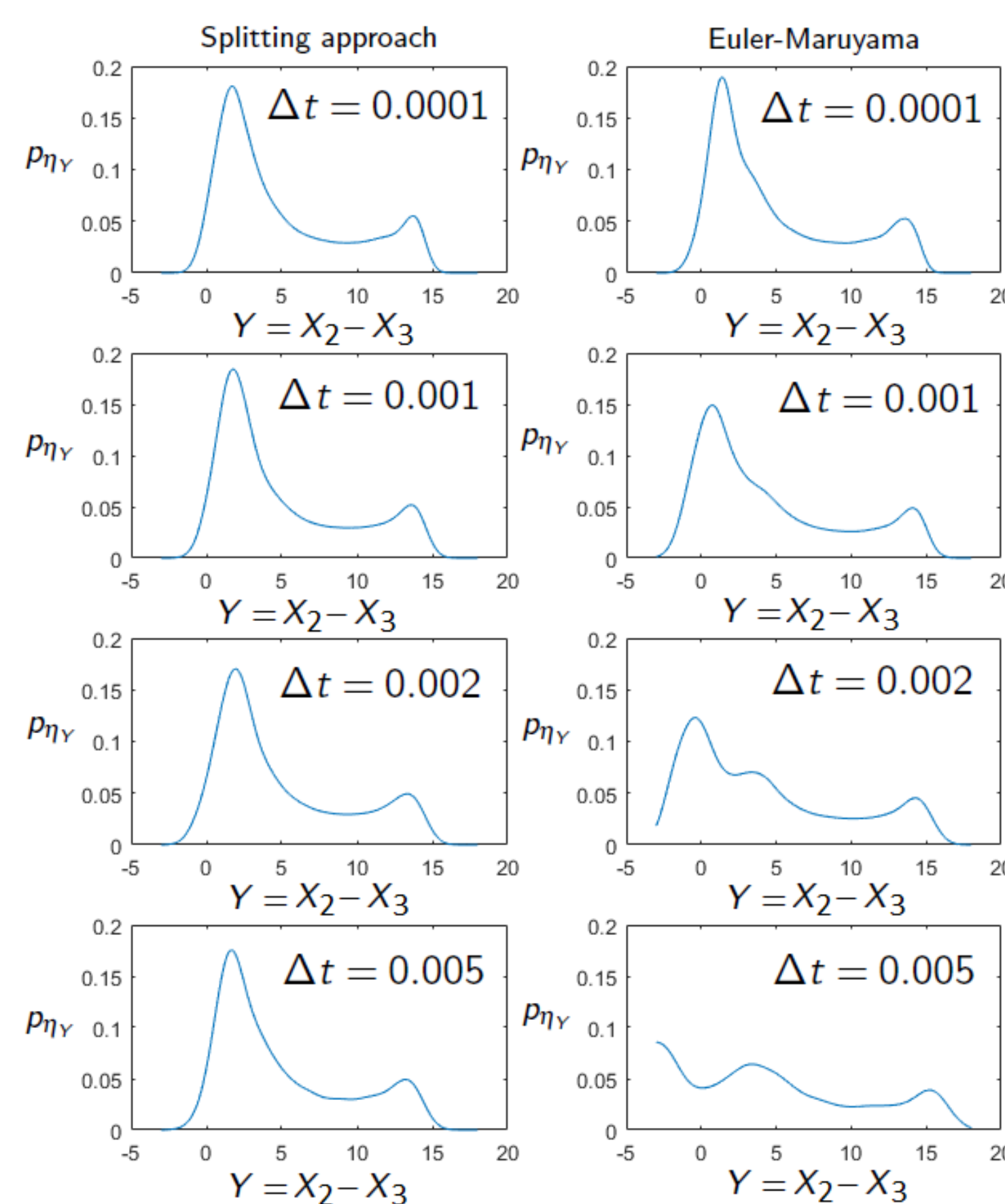
Key ingredients in simulation-based inference

1. Ability to simulate from the model (simulator).
2. Choice of the summary statistics.

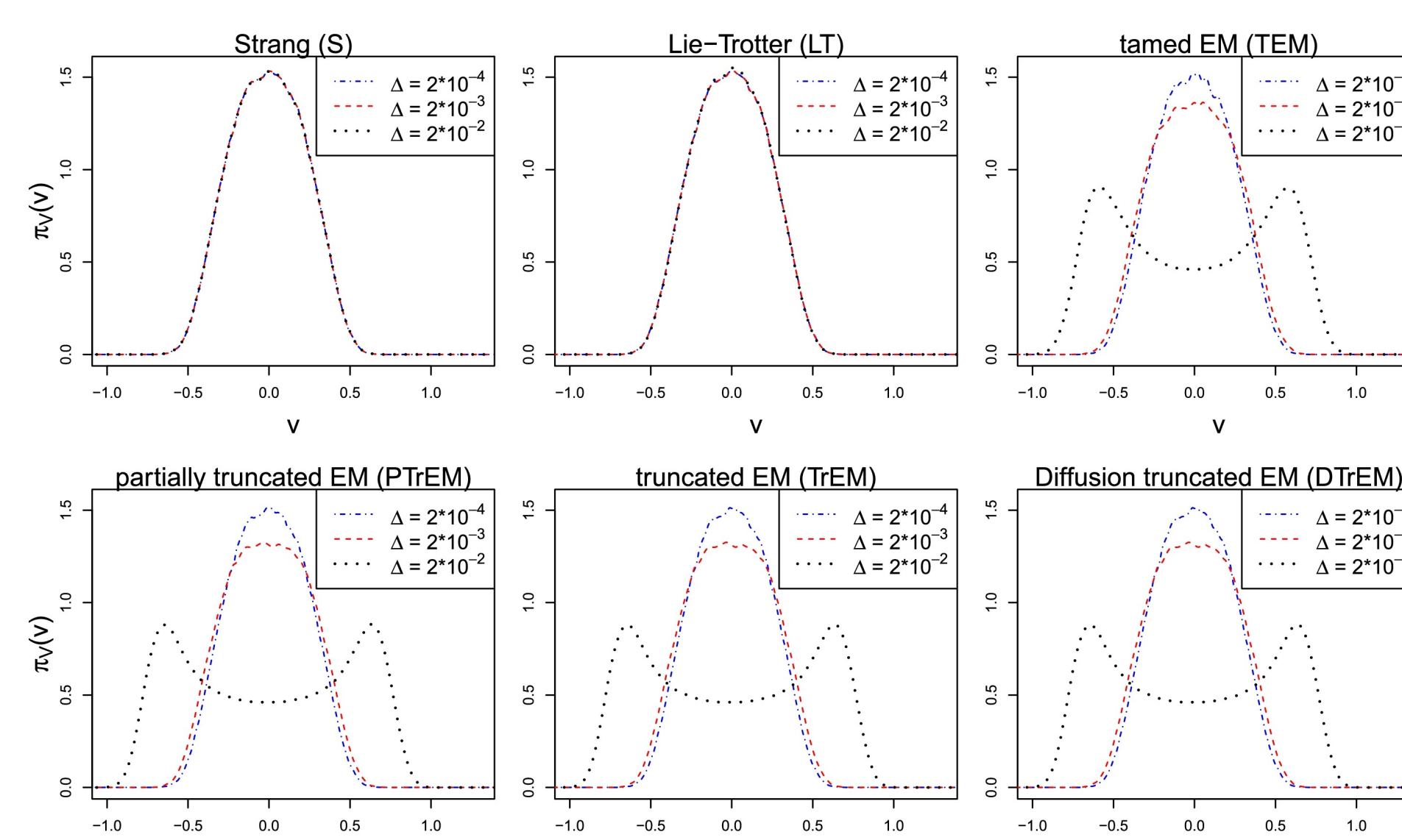
Ability to simulate from the model

Conditionally on θ^* from a proposal, we need to simulate a new realisation y_{θ^*} from the model (simulator).

Challenge: Exact simulation schemes are rarely available for SDEs.



Invariant density of the JRNMM estimated from simulated data [4]



Invariant density of the FHN estimated from simulated data [5].

1st Take home message

- Be sceptic with Taylor schemes (e.g. Euler-Maruyama and Milstein).
- Use reliable (convergent AND property-preserving) numerical schemes, here splitting schemes.

Numerical Splitting schemes in a nutshell

Consider $\tilde{X}_t \approx X_t$. How to simulate \tilde{X}_t given \tilde{X}_{t-1} ?

Step 1: Split the SDE into explicitly solvable sub-equations.

$$F(X_t; \theta) = \sum_{j=1}^d F^{[j]}(X_t; \theta), \quad \Sigma(X_t; \theta) = \sum_{j=1}^d \Sigma^{[j]}(X_t; \theta),$$

Step 2: Derive the explicit solutions of the sub-equations.

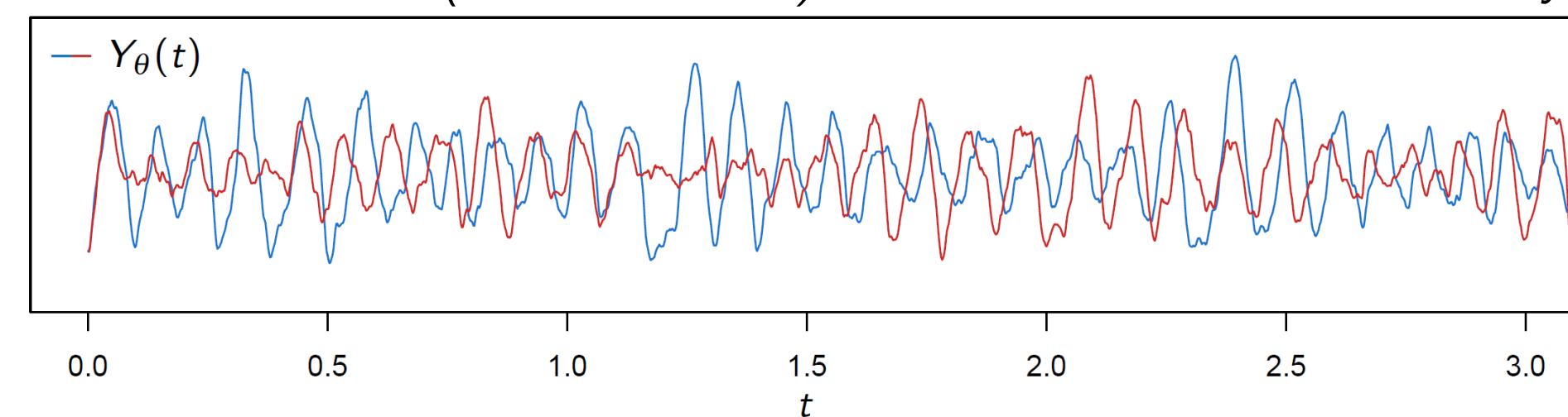
$$dX_t = F^{[j]}(X_t; \theta)dt + \Sigma^{[j]}(X_t; \theta)dW_t, j \in \{1, \dots, d\}.$$

Step 3: Compose the derived explicit solutions $X_t^{[j]} = \phi_t^{[j]}(x_0)$ (Strang approach)

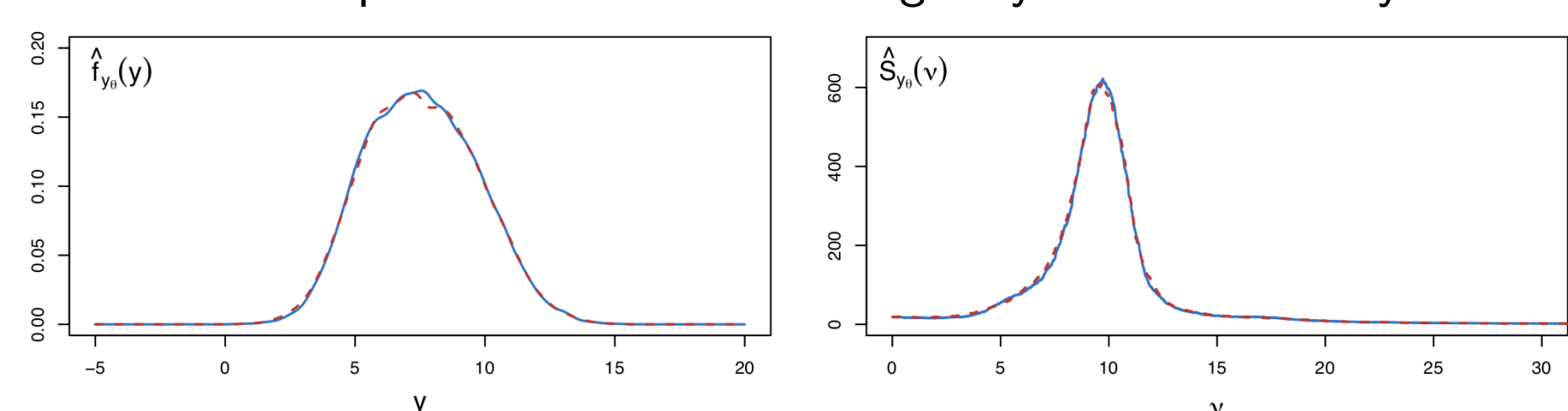
$$\tilde{X}_t = \left(\phi_{\Delta/2}^{[1]} \circ \dots \circ \phi_{\Delta/2}^{[d-1]} \circ \phi_{\Delta}^{[d]} \circ \phi_{\Delta/2}^{[d-1]} \circ \dots \circ \phi_{\Delta/2}^{[1]} \right) (\tilde{X}_{t-1}),$$

Choice of the summary statistics

How to account (and "remove!") for the intrinsic stochasticity?



Two realisations of Y_θ for the JRNMM with the same θ .
Proposal: Derive summaries based on the characterising model properties. **Goal:** map the data into something fully characterised by θ .



Estimated invariant density (left) and invariant spectral density (right) for the data above.

2nd Take home message: Incorporate SDE dynamics and structural properties to obtain summaries less sensitive to the intrinsic stochasticity of the model.

Structure-preserving ABC[1]

Reference table acceptance-rejection ABC Algorithm

Input: Observed data y from Y_θ .

Output: Samples from the posterior $\pi_{ABC}^\epsilon(\theta|s_y)$.

Choose a prior distribution $\pi(\theta)$ and a percentile p .

for $i = 1 : N$ **do**

1. Draw θ^* from the prior $\pi(\theta)$.

2. Conditionally on θ^* , simulate a new realisation y_{θ^*} from the model using the measure (property) preserving numerical splitting method.

3. Calculate the distance $D_i = \text{IAE}(\hat{S}_y, \hat{S}_{y_{\theta^*}}) + w \cdot \text{IAE}(\hat{f}_y, \hat{f}_{y_{\theta^*}})$, $w \geq 0$.

end for

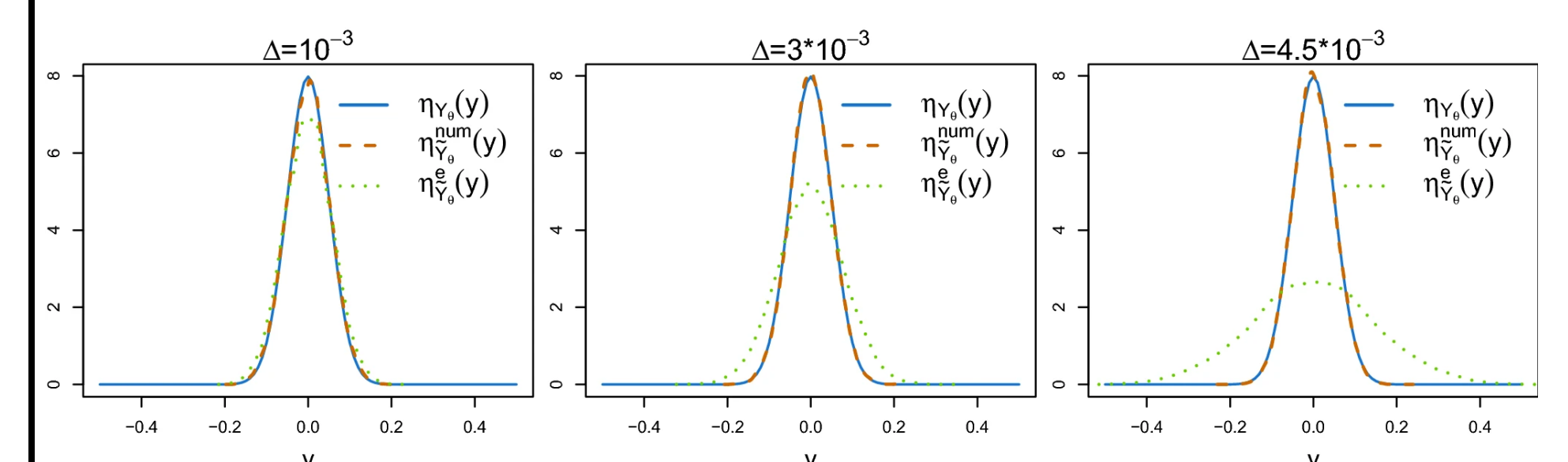
Compute ϵ as the percentage p of the calculated distances.

For $i = 1, \dots, N$, keep θ^i as a sample from the ABC posterior if $D_i < \epsilon$.

Key features: **inefficient** but **parallelisable**

$$\Rightarrow \pi(\theta|y) \stackrel{?}{=} \pi(\theta|s_y) \approx \pi_{ABC}^\epsilon(\theta|s_y) = \pi(\theta \mid d(s_y, s_{y_{\theta^*}}) < \epsilon)$$

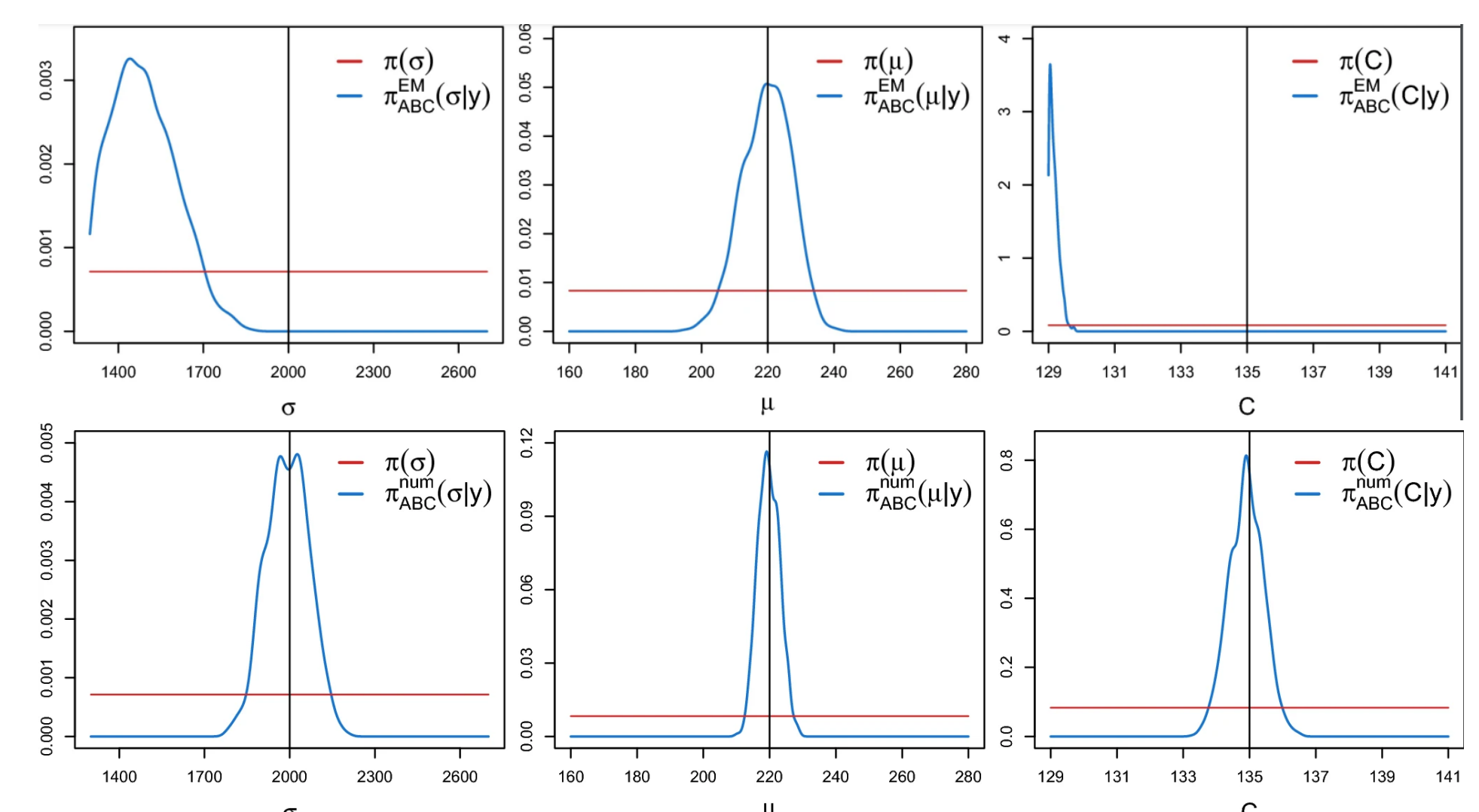
Stochastic harmonic oscillator with $\theta = \lambda$



- π_{ABC} : ABC posterior obtained with exact simulation;
- $\pi_{ABC}^{\text{Strang}}$: ABC posterior obtained with Strang splitting scheme;
- π_{ABC}^{EM} : ABC posterior obtained with Euler-Maruyama scheme.

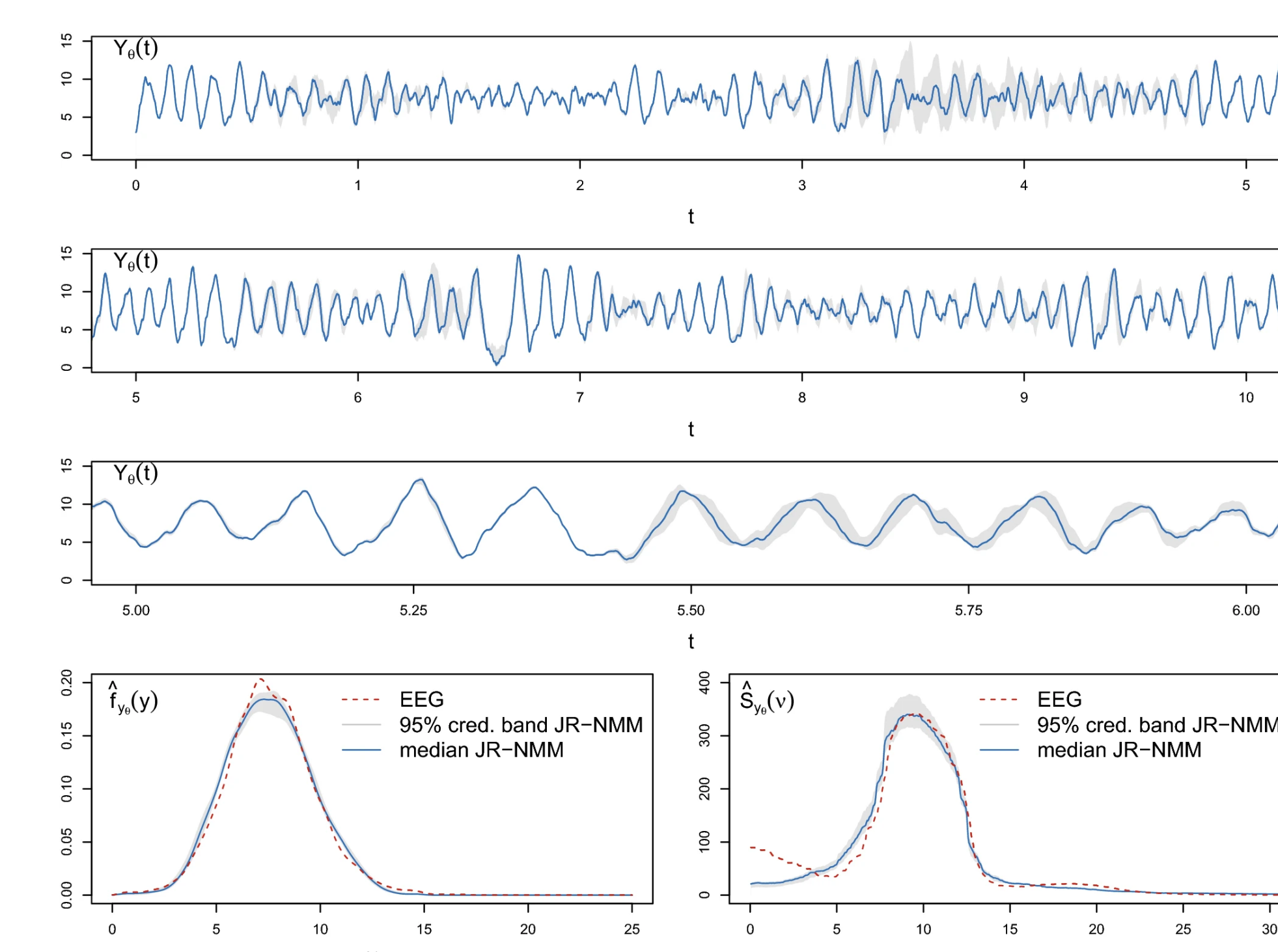
Stochastic JRNMM

Illustration on simulated data



ABC posteriors obtained with Euler-Maruyama scheme (top) vs splitting scheme (bottom).

Illustration on real EEG data



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- [1] E. Buckwar, M. Tamborrino, I. Tubikanec. Spectral density-based and measure-preserving ABC for partially observed diffusion processes. An illustration on Hamiltonian SDEs. *Stat. Comput.*, 30, 627–648, 2020.
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